



ГОСУДАРСТВЕННАЯ КОРПОРАЦИЯ ПО АТОМНОЙ ЭНЕРГИИ «РОСАТОМ»

# **STUDY OF PHYSICAL PROCESSES AT HIGH ENERGY DENSITIES WITH THE USE OF EXPLOSIVE MAGNETIC GENERATORS**

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**One of the methods to produce high energy density during modeling of physical processes and studies of material properties is to convert the kinetic energy of a high-velocity shell or a liner.**

**Traditionally, the liners are driven by:**

- **an explosive charge (HE) on gas-dynamic complexes;**
- **a current pulse on electrophysical facilities;**
- **radiation on laser facilities.**



**In accordance with the solution proposed by E.I. Zababakhin, the maximum velocity of the incompressible** liquid shell  $W_k$  is related to the detonation wave velocity D as

$$
\frac{W_k}{D} = \left[1 + \frac{27}{16\alpha} \left(1 - \sqrt{1 + \frac{16}{27}\alpha}\right)\right]
$$

**where**  $\alpha$  is the ratio between the mass of HE unit area and shell unit area.





**Shell velocity**  $W_k$  **as a function of detonation rate** 



At  $\alpha$ =12.5 -  $W_k/D$ =0.6. At the detonation velosity equal to D=9 km/s, we get  $W_k \approx 5.4$  km/s.

**Intensive shock wave**  $(\nu_0=0, p_0=0, \varepsilon_0=0)$ 

**When the impactor and the target are from the same material, the shock wave velocity is**  $v_1 = W_k/2 = 2.7$  km/s, **specific energy is**  $\varepsilon_1 = 0.004$  **MJ/g.** Pressure: **for aluminum shell**  $p_1=0.2$  **Mbar**;

**for iron shell**  $p_1=0.6$  **Mbar.** 



## **Scheme of loading**



## **Liner motion equation**

$$
\begin{cases}\n m \frac{d \vartheta}{dt} = -\frac{\mu_0 I^2}{4\pi r} \\
 \vartheta = \frac{dr}{dt}\n\end{cases}
$$

Here  $t -$  **time,**  $r -$  **coordinate,**  $\vartheta$  - **velocity**,  $I$ **current,**  $m = 2\pi\rho_0 r_0 h$  – **linear** mass ( $\rho_0$ , *h* and  $r_0$ **– matter density, thickness and initial position of the liner).**

**In dimensionless form**

**(**<sup>τ</sup> **- time of maximum current achievement***Imax***)**  $\widetilde{r}$  =  $r/r_0$ ,  $\widetilde{t}$  =  $t/\tau$ ,  $\widetilde{\vartheta}$  =  $\vartheta/\vartheta_0$  =  $\vartheta \cdot \tau/r_0$ 

$$
\begin{cases}\n\frac{d\tilde{\theta}}{d\tilde{t}} = -\Pi \frac{\tilde{I}^2}{\tilde{r}} \\
\tilde{\theta} = \frac{d\tilde{r}}{d\tilde{t}} \\
\tilde{B} = \frac{\mu_0 I_{max}^2 \tau^2}{8\pi^2 \rho_0 h r_0^3} \text{ determines} \\
\text{the scaling of lines.} \n\end{cases}
$$

**At** <sup>Π</sup>**=3 the liner travels half of initial radius at the moment of current maximum and its velocity is**  $v \approx 2r_0/\tau$  **(see the plot).** 



**Current**  $I/I_{max}$  = sin ( $\pi$   $\angle$   $\cdot$  $i$ / $\tau$ ), radius and velocity of **the liner as a function of time at** Π**=3.** 

The liner is stable during acceleration on the base  $N \le 5$  of initial **thicknesses** ( $h = r_0 / (2N)$ ). So,

$$
v = \left(\frac{4\mu_0 N}{\pi^2 \Pi}\right)^{1/4} \frac{1}{\rho_0^{1/4}} \cdot \sqrt{\frac{I_{max}}{\tau}} \qquad \Rightarrow \Psi[\text{ km/s}] = \frac{5.4}{\rho_0^{1/4} [g/\text{cm}^3]} \cdot \sqrt{\frac{I_{max}[\text{MA}]}{\tau [\text{mcs}]}}.
$$

**When the impactor and the target are made from the same material, the shock wave velocity is**  $v_1 = v/2$ .

**For the EMG with opening switches of microsecond range**

 $I/t \le 50$  **MA/** $\mu$ **s** and for  $AL$  ( $\rho_0 = 2.7$  g/cm<sup>3</sup>):  $v_1 = 15$  km/s;  $\varepsilon_1 = 0.1$  MJ/g;  $p_1 = 6$  Mbar.

**When the pulse front is reduced to 100 ns:**

 $v_1$ =45 km/s;  $\varepsilon_1$ =1 MJ/g;  $p_1$ =55 Mbar.

# **Lasers**





**Let's take that the LR energy is absorbed at density**  $\rho_{cr} = \pi A/Z \cdot m_p \cdot m_e \cdot (c/\lambda e)^2$ .

**Front conditions**  $\sqrt{ }$  $\overline{a}$  $(v_* - D) \cdot \rho_* = (v - D)$  $v_*$  - D)  $\cdot$   $\rho_*$  = (v - D  $-D) \cdot \rho_* = (\nu - D).$  $\rho_* = (v - D) \cdot \rho$ *\* \**  $\left\{ \begin{matrix} (x_1 - D) P_1 \\ P_2 + P_2 (v_1 - D)^2 = p + \rho (v - D) \end{matrix} \right\}$  $p_* + \rho_*(v_* - D)^2 = p + \rho(v - D)^2$  $+ \rho_* (v_* - D)^2 = p +$ ⎨  $\rho_{\scriptscriptstyle\star}$  ( $v_{\scriptscriptstyle\star}$  - D  $\bar{f}$  =  $p + \rho$ *\* \* \**  $\overline{a}$  $(v_*$  - D) **2 a b p (v-D)<sup>2</sup>**  $(v - D)$  $p_*$   $(v_*$  -  $D)^t$  *S*  $\vert$ *\* \**  $\left[\varepsilon_{*} + \frac{P_{*}}{\rho_{*}} + \frac{(v_{*}-D_{*})}{2} + \frac{D_{*}}{\rho_{*}(v_{*}-D)}\right] = \varepsilon + \frac{P_{*}}{\rho} + \frac{(v-1)}{2}$ ε ε  $\left( \rho_* \right)$  2  $\rho_* (\nu_* - D)^{-c}$   $\rho$  $(v_*-D)$  $\frac{1}{2}$  $v_*$  –  $\boldsymbol{D}$  $\rho_*$ , 2,  $\rho_*$ *\* \* \** **Index «\*» relates to the values behind the wave front.** *S* **is laser radiation flux power. Intensive shock wave**  $(v_0=0, p_0=0, \varepsilon_0=0)$  $\begin{cases}\n\boldsymbol{p}_1 = \frac{\boldsymbol{\delta}}{\boldsymbol{\delta}-1} \cdot \boldsymbol{\rho}_0 \boldsymbol{v}_1^2, \\
\boldsymbol{\varepsilon}_1 = \frac{\boldsymbol{v}_1^2}{2}, \quad \boldsymbol{\delta} = \frac{\boldsymbol{\rho}_1}{\boldsymbol{\rho}_0} \text{-compression}\n\end{cases}$ 

**Evaporation wave front Velocity of plasma flow is**  $v - D_1 = -c_0$ **. At adiabatic process:**  $\bullet$  -sound speed  $c_0 = (\gamma p/\rho_{cr})^{1/2}; \quad \text{pressure } p = 1/\gamma \rho_{cr} c_0^2.$ For ideal gas  $\varepsilon = \frac{p}{\sqrt{p}} = \frac{1}{2}$ **Taking this into account and the condition on the front of the intensive shock wave** After the transformations we have  $(\rho_{cr}/\rho_0 \rightarrow 0, \ \delta/(\delta 1) \rightarrow 1)$  $(\gamma - 1)\rho_{cr}$   $\gamma(\gamma - 1)$ **2**  $=\frac{p}{(\gamma-1)\rho_{cr}^{\gamma}}=\frac{c_0}{\gamma(\gamma-1)}$  $\varepsilon = \frac{p}{\sqrt{c}} = \frac{c}{\sqrt{c}}$ *cr*  $\overline{a}$  $\overline{a}$ ⎩  $\overline{a}$  $\overline{a}$ ⎨  $\sqrt{ }$  $\left(\frac{c_0^2}{2} - \frac{\delta + 1}{\delta - 1} \cdot \frac{v_1^2}{2}\right) = \frac{S}{\rho_{cr}}$ ⎠ ⎞  $\parallel$  $\left(\frac{\gamma+1}{\gamma-1}-\frac{1}{\delta^2}\right)$  $\sqrt{2}$ ⎠ ⎞  $\parallel$  $\frac{\delta}{\delta - 1} v_1^2 = \frac{\rho_{cr}}{\rho_0} c_0^2 \cdot \left( \frac{\gamma + 1}{\gamma} - \frac{1}{\delta} \right)$ **0 2 1 2 0 2 0 2 2 0 2 0 0 2 1 1 2 1 2 1 1 1 1 1 1** *c*  $c_0^2$   $\delta$  + 1  $v_1^2$  *S*  $v_1^2 = \frac{P_{cr}}{C}c$ *cr cr cr cr*  $\delta$  -1 2  $\rho$ δ ρ ρ  $\gamma - 1 \delta$ γ ρ ρ γ δ γ ρ ρ δ δ  $\overline{a}$  $\sqrt{ }$ 

$$
\begin{cases}\nP_1 \approx 2 \cdot \rho_{cr} c_0^2 \\
\varepsilon_1 = \frac{v_1^2}{2} = \frac{\delta - 1}{\delta} \frac{\rho_{cr}}{\rho_0} c_0^2 \cdot \left(\frac{\gamma + 1}{\gamma} - \frac{1}{\delta} \cdot \frac{\rho_{cr}}{\rho_0}\right) \approx \frac{\gamma + 1}{\gamma} \cdot \frac{\rho_{cr}}{\rho_0} c_0^2 \\
S = \frac{1}{2} \cdot \rho_{cr} \cdot c_0^3 \cdot \left(\frac{\gamma + 1}{\gamma - 1} - \frac{\delta + 1}{\delta} \cdot \frac{\rho_{cr}}{\rho_0} \cdot \frac{\gamma + 1}{\gamma} + \frac{1}{\delta} \cdot \frac{\rho_{cr}^2}{\rho_0^2}\right) \approx \frac{1}{2} \cdot \frac{\gamma + 1}{\gamma - 1} \cdot \rho_{cr} \cdot c_0^3\n\end{cases}
$$

**The limiting value is**  $S_m \approx 10^{15} \text{ W/cm}^2$ . At  $\lambda = 1 \text{ }\mu\text{m} - \rho_c \approx 4 \cdot 10^{-3} \text{ g/cm}^3$ .

In the result for aluminum  $(\rho_0=2,7 \text{ g/cm}^3)$  we get:  $c_0 = 1,26 \cdot 10^8$  cm/s;  $v_1 \approx 62$  km/s;  $\varepsilon_1 \approx 1.9$ MJ/g;  $p_1 \approx 100$  Mbar.

# **Comparison of the research methods**









**Specific energy and pressure as a function of time**





# **Of interest is the study of spall damage, dynamic strength, ejecta at shock wave release to surface.**



- **Outer view of experimental facility: 1- HEMG;**
- **2 - units of current peaking and interruption;**
- **3 - wave line;**
- **4 - explored specimens protection;**
- **5 - load**





**Loading scheme: 1 – driven liner; 2 – cylindrical targets from explored material.** 

**Current pulse: amplitude to 10 MA; controlled duration to ~30 µs;** rise and drop time  $\sim$ 2  $\mu$ s.







### **The results allowed verifying the numerical models of spall damage and recollection of damaged medium.**



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#### Damage growth and recollection in aluminum under axisymmetric convergence using a helical flux compression generator

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# **We have started the experiments to study the shear strength of beryllium**



**Target unit**



**The** *Ве* **specimens 3, 4, 5 mm thick are enveloped into** *Al* **1 mm thick to collect the debris in case of fragmentation.**

**In order to avoid the spall damage in** *Be***, the targets were placed on the aluminum "sacrificial" substrate 3 mm thick.**

# **The current is flowing in 2 mm-thick** *Al* **liner.**

In the first experiment the liner was driven to  $\sim 1$  km/s. **that provided pressure of ~10 GPa during impact on the target.**

**The expected information on of the liner and targets velocities was obtained.**

**We managed to avoid the targets implosion to the axis. The test specimens were recovered for metallographic analysis.**





**Target unit with** *Ве***: before experiment –а; after experiment –b.**





The shear strength data at the strain rate  $\epsilon = 0.5 \div 1.10^4 \text{ s}^{-1}$  have been obtained.

In the next experiment we plan to get higher levels of plastic deformation  $\varepsilon \sim 0.4 \div 1.0$  while **preserving the strain rates within the same range.**

# **The ejecta of lead at shock wave release to the surface**





**A series of experiments was realized. 5-6 specimens were loaded in every experiment.**

•**The specimens differ in surface finish - amplitude to 80 µm, wave length to 400 µm.**

**.**

•*Cu*-liner thickness is h=1 mm. The current is the same in all experiments  $J_m = 10$  MA,  $\tau = 30$  µs.

•**The radius of the samples' surface changed the from experiment to experiment, that allowed varying pressure from 20 to 40 GPa.**

**In experiments we measured the current, the velocities of the liner, of ejecta–***v<sup>п</sup>* **and of lavsan**  $\tan \nu_L$  with linear mass  $m_L$  (PDV). The linear mass of ejecta *m* was estimated by

$$
m = m_L \cdot \frac{v_L}{v_n - v_L}
$$

**The ejecta processes were studied without dynamic diversity of effect caused by the system of HE initiation and by instabilities on the detonation front.**





**In the range of shock wave pressure of 20 - 40 GPa lead can both stay solid and turn to liquid at unloading wave.**

**Analysis of results of the experimental series (green dots) will make it possible to evaluate the effect of the phase state of lead on the parameters of ejecta process.** 



# **Of interest are the studies of turbulent mixing (TM) and equations-of-state (EOS) of matter.**

# **Turbulent mixing (TM)**

- The study with solid bodies on gas-dynamic complexes at velocities of  $\sim$ 5 km/s is impossible because of the **elastic-plastic effects impeding the development of TM.**
- Velocity of  $\geq 10$  km/s can be achieved in the three-cascade systems or on light gas guns. The thicknesses of the **shells (fractions of mm) are not enough for radiographic imaging.**
- The models are verified using data obtained at acceleration to  $10^5 g_0$  in the experiments with gasses.
- DEMG allows driving cylindrical liners  $\sim$ 1.5 mm thick to velocities of 10-20 km/s. This will broaden the range of studies to  $10^9$ *g*<sup>0</sup>.



Calculated r - t diagrams of TM zone boundaries at deceleration of Cu plate 1.5 mm thick driven to 10 km/s against polyethylene with thickness: a) 10 cm; b) 3 cm.



**It is planned to conduct studies of TM zone development at deceleration of copper shells on a layer of light substance (polyethylene, water).**

**In addition, it is possible to study the EOS of substances during isentropic and shock loading by pressure of 3-4 Mbar.**





**Experimental test bench layout:**

- **- DEMG with diameter 0.25 m - 1;**
- **- electrically exploded current opening switch - 2;**
- **- system of protection from shock wave and debris - 3;**
- **- radial and longitudinal x-ray imaging- 4;**
- **-** *PDV* **technique- 5;**
- **- optical and** *B***-***dot* **techniques to measure current pulses.**



**Time dependence of current and voltage on electrically exploded opening switch**



**Study of TM zone formation**

# **Experimental diagrams**



**Study of TM zone interaction with reflected shock wave**





**Only the current source on the basis of EMG is destroyed during the operation.**

- **- current source on the basis of HEMG - 1 and DEMG-2 of middle class (** $\varnothing$  **0.4 m);**
- **- unit of current peaking to ~ 100 ns - 4 placed into a protective housing – 3.**

**Vacuum system of the current peaking unit and recording path comprises:**

- **- flexible vacuum section – 5;**
- **- gate valves– 7;**
- **- protective constructions – 6;**
- **- vacuum station – 9 located inside bunker - 8.**

**The test bench can be used to conduct experiments on Z-pinch implosion by the current ~ 25 MA for the time of ~120 ns**. **It will make it possible:**

**- to achieve pressures to 40 Mbar:**

**- to generate X-rays with the energy to ~3 MJ for the time ~10 ns.**

**Further increase of pressure and X-radiation energy is possible in single experiments with the use of super-power disk EMG 1 m in diameter.**

**The problematic point is realization of current peaking to ~ 100 ns.**



In the process of current  $J_0$  switching from the inductive storage  $L_v$ **to** the load equal to inductance  $(L_n = L_v)$  the current is divided in half  $J_n = J_0/2$ , the energy decreases by a factor of 4.



# **There are two ideas for realization of current switching for the time of ~ 100 ns:**

# •**electrically exploded corrugated current opening switch**

**S.G. Garanin, A.V. Ivanovsky and L.S.Mkhitariyan An ICF system based on Z-pinch radiation produced by an explosive magnetic generator//Nuclear Fusion, 2011, V.51, N10 (15pp).**

### •**magneto-dynamic current opening switch**

**A.A.Bazanov, A.V.Ivanovsky, V.Sh.Shaidullin Magneto-dynamic current opening switch with submicrosecond time switching // ZhTF, 2010.**

**Schematic Outer view**





